

**Curriculum Vitae**  
**Sergiu Nedevschi, PhD E. E.**  
**Professor of Computer Science**  
Computer Science Department  
Technical University of Cluj-Napoca  
Romania



**Full Name:** Sergiu S. Nedevschi

**Nationality:** Romanian

**Job Title:** Professor with Computer Science Department, manager of the Image Processing and Pattern Recognition Research Center.

**Date of Birth:** 09.10.1951

**E-mail Address/ Web Page:** [Sergiu.Nedevschi@cs.utcluj.ro](mailto:Sergiu.Nedevschi@cs.utcluj.ro) / [Sergiu Nedevschi's homepage \(utcluj.ro\)](#)

**Work Phone Number / Fax Number :** +40 264 401235 / +40 264 592055

**Work Address:** Technical University of Cluj-Napoca, 28 Memorandumului Street, 400114, Cluj-Napoca, Romania

**Academic Qualifications:**

1975: Graduate of Technical University of Cluj-Napoca, Msc. in Electrical Engineering;

1993: PhD in Electrical Engineering at Technical University of Cluj-Napoca, Romania (thesis title "Model Based Object Recognition").

**Employment:**

1975-1983: Senior Research Fellow, Research Institute for Computer Technologies, Cluj-Napoca branch, (I.T.C.Cluj filiala Cluj-Napoca);

1983-1991: Assistant Professor, Computer Science Department, TUCN;

1991-1994: Senior Assistant Professor, Computer Science Department, TUCN;

1994-1998: Associate Professor, Computer Science Department, TUCN;

1998-: Professor, Computer Science Department, TUCN;

2000-2004: Head of Computer Science Department, TUCN;

2004-2012: Dean of Faculty of Automation and Computer Science, TUCN;

2012-2020: Vice Rector of TUCN in charge with Scientific Research and ICT

**Teaching:**

I am currently teaching for English and Romanian classes the following courses:

- Image Processing (3<sup>th</sup> year)
- Pattern Recognition (4<sup>th</sup> year)
- Artificial Vision (master)
- Artificial Vision for Autonomous Driving (master)

**Research areas:**

- Image Processing and Pattern Recognition
- Computer Vision and Artificial Intelligence
- Machine Learning and Deep Learning based Perception
- 2D Sensors Based Perception (grey and colour cameras)
- 2D and 3D Sensors Based Perception (Stereo, LiDAR, RADAR)
- Semantic, Instance and Panoptic Semantic Segmentation, Structure from motion, Stereovision, LiDAR and RADAR data Processing, Geometry and Semantic fusion, Object and Pedestrian Detection Tracking and Recognition, Environment Representation, Risk Assessment

- Intelligent Vehicles, Driving Assistance Systems, Autonomous Mobile Systems
- Medical Image Processing

### Research Activity:

I was involved in 80 research projects, being the coordinator, local coordinator or manager of 62 of them. I have coordinated or managed 29 international projects from which 6 FP7, 1 Horizon 2020, 19 with companies and 3 bilateral projects.

The research activity carried out in the Image Processing and Pattern Recognition Research Lab established in 1998 and upgraded to Research Center in 2010.

### Selected Projects:

1. “3D perception for autonomous vehicles based on deep learning - DeepPerception”, PN III-P4-PCE-2021-1134, (2022-2024) - S. Nedevschi, project manager
2. “Integrated Semantic Visual Perception and Control for Autonomous Systems - SEPCA”, PN-III-P4- PCCF, 293/ 21.08.2018 - S. Nedevschi, local coordinator. (2018-2022)
3. “Multispectral environment perception by fusion of 2D and 3D sensorial data from the visible and infrared spectrum – MULTISPECT”, PN-III-P4-ID-PCE-2016-0727, - S. Nedevschi project manager. (2017-2020)
4. “Automated Urban Parking and Driving – UP-Drive”, Horizon 2020, partners VW, ETH Zurich, IBM Zurich, University of Praga, - S. Nedevschi, local coordinator. (2016-2019)
5. “Reconfigurable ROS-based Resilient Reasoning Robotic Cooperating Systems - R5-COP”, FP7 ARTEMIS, - S. Nedevschi, local coordinator. (2014-2017)
6. “Image processing based on stereo and Mono cameras for Driver Assistance Systems”, research project funded by Robert Bosch, Germany, - S. Nedevschi, coordinator (2013-2016)
7. “PAN-Robots - Plug And Navigate ROBOTS for smart factories”, FP7, partners SICK Germany, VTT Finland, University of Modena, Electric 80, - S. Nedevschi, local coordinator. (2012 – 2015),
8. “Co-operative Mobility Services of the Future – CoMoSeF”, Celtic Plus project, - S. Nedevschi, local coordinator. (2012-2015)
9. “Cooperative Advanced Driving Assistance System Based on Smart Mobile Platforms and Road Side Units – SmartCoDrive”, Romanian Ministry of Education and Research, code PN II PCCA 2011 3.2-0742 from 03.07.2012, - S. Nedevschi, coordinator. (2012-2016)
10. “Multi-scale and multi-modal perception of the 3D dynamic environments by fusion of the dens stereo, dens optical flow and visual odometry data - MULTISENS”, Romanian Ministry of Education and Research, code PN II IDEI 2011 - S. Nedevschi, project manager. (2012-2016)
11. “DRIVE C2X” - Accelerate cooperative mobility, FP7, - S. Nedevschi, local coordinator. (2011-2013).
12. “INSEMTIVES - Incentives for Semantics, FP7, S. Nedevschi - local coordinator. (2010-2012)
13. “Large Scale Semantic Computing Semantic Web technologies distributed reasoning probabilistic reasoning web-scale inference information retrieval – LarkC”, FP7, (2010-2011), S. Nedevschi, local coordinator. (2010-2011)
14. “Perceptia senzoriala, modelarea si reprezentarea modelului lumii pentru sisteme de asistare a conducerii - PERSENS”, Romanian Ministry of Education and Research, code PN-II-IDEI exploratory research, - S. Nedevschi, project manager. (2009-2011),
15. “Cooperative Intersection Safety – INTERSAFE 2”, FP7, partners IBEO, VW, BMW, Volvo, INRIA, UTC-N, - S. Nedevschi, local coordinator. (2008-2011)

### Publications:

|   |     |
|---|-----|
| Books:                                      | 20  |
| Chapters in Books:                          | 8   |
| Papers:                                     | 432 |
| In proceedings of international conferences | 290 |
| In journals                                 | 106 |
| In ISI journals                             | 47  |

### Selected publications:

1. A. Petrovai, S. Nedevschi, "Semantic Cameras for 360-degree Environment Perception in Automated Urban Parking and Driving", *IEEE Transactions on Intelligent Transportation Systems*, vol. 23, Issue 10, pp. 17271-17283, Oct 2022.
2. V.C. Miclea, S. Nedevschi, "Monocular Depth Estimation With Improved Long-Range Accuracy for UAV Environment Perception", *IEEE Transactions on Geoscience and Remote Sensing*, Vol. 60, AN 5602215, JAN 2022.
3. A. Petrovai, S. Nedevschi, "Fast Panoptic Segmentation with Soft Attention Embeddings", *SENSORS*, Vol. 22, Issue 3, AN: 783, FEB 2022.
4. H. Florea, A. Petrovai, I. Giosan, F. Oniga, R. Varga, S. Nedevschi, "Enhanced Perception for Autonomous Driving Using Semantic and Geometric Data Fusion", *SENSORS*, Vol. 22, Issue 3, AN: 783, JUL 2022.
5. A. Petrovai, S. Nedevschi, Time-Space Transformers for Video Panoptic Segmentation, *Proceedings of WACV, Hawaii, USA, 3-5 January 2022*, pp. 925-934
6. Petrovai, S. Nedevschi, "Pseudo-annotation based unsupervised monocular depth estimation", *2022 Conference on Computer Vision and Pattern Recognition (CVPR)*. 19-24 June 2022, New Orleans, SUA.
7. R. Brehar, M.P. Muresan, M. Tiberiu, C. Vancea, N. Mihai, S. Nedevschi, "Pedestrian Street-Cross Action Recognition in Monocular Far Infrared Sequences", *IEEE ACCESS*, Vol. 9, pp. 74302-74324, JUN 2021.
8. M.P. Muresan, S. Nedevschi, R. Danescu, "Robust Data Association using Fusion of Data-Driven and Engineered Features for Real Time Pedestrian Tracking in Thermal Images", *SENSORS*, Vol. 21 Issue 23, AN 8005, NOV 2021.
9. V. Miclea, S. Nedevschi, Real-Time Semantic Segmentation-Based Stereo Reconstruction, *IEEE Transactions on Intelligent Transportation Systems*, 21(4),8751135, pp. 1514-1524, APR 2020.
10. R. Brehar, D. Mitrea, F. Vancea, T. Marita, S. Nedevschi, M. Lupsor, M. Rotaru, R. Badea, Comparison of Deep-Learning and Conventional Machine-Learning Methods for the Automatic Recognition of the Hepatocellular Carcinoma Areas from Ultrasound Images, *SENSORS*, Vol. 20, Issue 11, AN: 3085, JUN 2020.
11. M.P. Muresan, I. Giosan, S. Nedevschi, "Stabilization and Validation of 3D Object Position Using Multimodal Sensor Fusion and Semantic Segmentation", *SENSORS*, Vol. 20, Issue 4, AN: 1110, FEB 2020, DOI10.3390/s20041110
12. A. Petrovai, S. Nedevschi, Multi-Task Network for Panoptic Segmentation in Automated Driving", *Proceeding of 2019 IEEE Intelligent Transportation Systems Conference (ITSC)*, Auckland, New Zealand, 26-30 October, 2019.
13. S.E.C. Deac, I. Giosan, S. Nedevschi, "Curb Detection in Urban Traffic Scenarios Using LiDARs Point Cloud and Semantically Segmented Color Images", *Proceeding of 2019 IEEE Intelligent Transportation Systems Conference (ITSC)*, Auckland, New Zealand, 26-30 October, 2019.
14. A. Petrovai, S. Nedevschi, "Efficient instance and semantic segmentation for automated driving", *Proceeding of 2019 IEEE Intelligent Vehicles Symposium (IV 2019)*, Paris; France; 9-12 June, 2019, pp. 2575-2581.
15. AD Costea, A. Petrovai, S. Nedevschi, "Fusion Scheme for Semantic and Instance-Level Segmentation", *Proceedings of 2018 IEEE Intelligent Transportation Systems Conference (ITSC)*, Maui, Hawaii, USA, November 4-7, 2018
16. V. Miclea, S. Nedevschi, "Real-Time Stereo Reconstruction Failure Detection and Correction Using Deep Learning", Maui, Hawaii, USA, November 4-7, 2018
17. V. Miclea, S. Nedevschi, "Real-Time Semantic Segmentation-Based Depth Upsampling Using Deep Learning", *Proceedings of 2018 IEEE Intelligent Vehicles Symposium (IV)*, Changshu, China, June 26-30, 2018
18. Lorenzo Sabattini, Mika AikioS,...,Sergiu Nedevschi, Cristian Secchi, and Kay Fuerstenberg, "The PAN-Robots Project: Advanced Automated Guided Vehicle Systems for Industrial Logistics", *IEEE ROBOTICS & AUTOMATION MAGAZINE*, pp. 55-64, MARCH 2018,
19. M. Drulea, A. Vatavu, Sz. Mandici, S. Nedevschi, "An Omnidirectional Stereo System for Logistic Plants. Part 1: Calibration And Multi-Channel Rectification", *Proceedings of Romanian Academy*, series A, Volume: 18 Issue: 1 pp. 89-97, 2017.

20. M. Drulea, A. Vatavu, Sz. Mandici, S. Nedevschi, "An Omnidirectional Stereo System for Logistic Plants. Part 2: Stereo Reconstruction and Obstacle Detection Using Digital Elevation Maps", *Proceedings of Romanian Academy*, series A, Volume: 18 Issue: 3 pp. 265-272, 2017.
21. VC Miclea, S Nedevschi, "Semantic segmentation-based stereo reconstruction with statistically improved long range accuracy", *Proceedings of 2017 IEEE Intelligent Vehicles Symposium (IV)*, Redondo Beach, CA, USA, June 11-14, 2017, pp. 1795-1802.
22. A. Costea, S. Nedevschi, "Traffic Scene Segmentation based on Boosting over Multimodal Low, Intermediate and High Order Multi-range Channel Features", in *Proceedings of 2017 IEEE Intelligent Vehicles Symposium (IV)*, Redondo Beach, CA, USA, June 11-14, 2017, pp. 74-81.
23. R. Varga, AD. Costea, H. Florea, I. Giosan, S. Nedevschi, "Super-sensor for 360-degree Environment Perception: Point Cloud Segmentation Using Image Features", *Proceedings of 2017 IEEE Intelligent Transportation Systems Conference (ITSC)*, Yokohama, Japan, best student paper award, 16-19 October, 2017, pp. 1-8.
24. AD Costea, R Varga, S Nedevschi, "Fast Boosting Based Detection Using Scale Invariant Multimodal Multiresolution Filtered Features", *Proceedings of 2017 IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2017, pp. 993-1002.
25. A. Costea, S. Nedevschi, "Semantic Channels for Fast Pedestrian Detection", *Proceedings of 2016 IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Las Vegas, USA, June, 2016, pp. 2360-2368.
26. C. Vicas, S. Nedevschi, "Detecting Curvilinear Features Using Structure Tensors", *IEEE Transactions on Image Processing*, vol. 24, no. 11, pp. 3874 – 3887, Nov. 2015.
27. M. Negru, S. Nedevschi, RI Peter, Exponential Contrast Restoration in Fog Conditions for Driving Assistance, *IEEE Transactions on Intelligent Transportation Systems*, Vol. 16, No. 4, pp. 2257-2268, AUG 2015.
28. V. Popescu, S. Nedevschi, R. Danescu, T. Marita, A Lane Assessment Method Using Visual Information Based on a Dynamic Bayesian Network, *JOURNAL OF INTELLIGENT TRANSPORTATION SYSTEMS*, Vol. 19. No. 3, pp. 225-239, JUL 2015.
29. A. Vatavu, R. Danescu, S. Nedevschi, "Stereo-vision-Based Multiple Object Tracking in Traffic Scenarios Using Free-Form Obstacle Delimiters and Particle Filters", *IEEE Transactions on Intelligent Transportation Systems*, Vol. 16, No. 1, pp. 498-511, FEB. 2015.
30. R. Danescu and S. Nedevschi, "A Particle-Based Solution for Modeling and Tracking Dynamic Digital Elevation Maps", *IEEE Transactions on Intelligent Transportation Systems*, Vol. 15, No. 3, pp.: 1002-1015, JUN 2014.
31. M. Drulea, S. Nedevschi, "Motion estimation using the correlation transform", *IEEE Transactions on Image Processing*, vol. 22, no. 8, pp. 3260-3270, DEC 2013.
32. S. Nedevschi, V. Popescu, D. Radu, M. Tiberiu, F. Oniga, "Accurate Ego-Vehicle Global Localization at Intersections through Alignment of Visual Data with Digital Map", *IEEE Transactions on Intelligent Transportation Systems*, vol.14, Issue 2, pp. 673-687, JUN 2013.
33. R. Varga, S. Nedevschi, "Label transfer by Measuring Compactness", *IEEE Transactions on Image Processing*, MAY 2013.
34. C. Pantilie, S. Nedevschi, "SORT-SGM: Sub-pixel Optimized Real-Time Semi-Global Matching for Intelligent Vehicles", *IEEE Transactions on Vehicular Technology*, vol. 61, no. 3, pp. 1032-1042, MAR 2012.
35. I. Haller, S. Nedevschi, "Design of Interpolation Functions for Sub-Pixel Accuracy Stereo-Vision Systems", *IEEE Transactions on Image Processing*, vol. 21, no. 2, pp. 889-898, FEB 2012.
36. S. Nedevschi, S. Bota, C. Tomiuc, "Stereo-Based Pedestrian Detection for Collision-Avoidance Applications", *IEEE Transactions on Intelligent Transportation Systems*, 2009, vol. 10, no. 3, pp. 380-391, 2009.
37. R. Danescu, S. Nedevschi, "Probabilistic Lane Tracking in Difficult Road Scenarios Using Stereo-vision", *IEEE Transactions on Intelligent Transportation Systems*, vol. 10, no. 2, pp. 272-282, 2009.
38. S. Nedevschi, C. Vancea, T. Marita, T. Graf, "Online Extrinsic Parameters Calibration for Stereo-vision Systems Used in Far-Range Detection Vehicle Applications", *IEEE Transactions on Intelligent Transportation Systems*, vol. 8, no. 4, pp. 651-660, 2007.

**Citations:**

h-index 26 in ISI Web of Science and 2573/2118 citations

h-index 30 in Scopus and 3604 citations

h-index 39 in Google Academic and 5984 citations

**Activity:**

- Associate Editor for IEEE Transactions on Intelligent Transportation Systems
- Associate Editor for IEEE Transactions on Intelligent Vehicles
- Associate Editor for Electronic Letters on Computer Vision and Image Processing
- Reviewer: IEEE Transactions on Intelligent Transportation Systems, IEEE Transactions on Vehicular Technologies, IEEE Transactions on Image Processing, IEEE Transactions on Pattern Analysis, Optics and Lasers in Engineering, Sensors, etc.
- External PhD and habilitation evaluator at universities from Romania, France, Sweden, Ireland, Australia, Pakistan
- Invited professor at Mercedes-Benz Research and Development North America, Sunnyvale CA, USA, VTT Tampere and Helsinki, Finland, SICK Hamburg Germany, Chonnam National University from Gwangju, Korea, University of Limerick, Ireland, Technical University of Braunschweig and Technical University of Muenchen, Germany.
- Conference Chair, PC co-chair, PC member, member in the local organizing committee, session chair of more than 50 international conferences and workshops: IEEE IV Symposium, IEEE ITSC, IEEE ICCP, IEEE INES, CVVT:E2M, ICINCO, CSCS, SINTES, IEEE SACII. IEEE AQTR
- Member of: IEEE Computer Society, IEEE Signal Processing Society, IEEE Intelligent Transportation Society, IEEE Romania Computers Chapter
- Member of IEEE Romania Section Committee in charge with educational activities
- Member of Self Driving Automobiles technical committee of IEEE Intelligent Transportation Society, since 2018
- Evaluator of National Council of Scientific Research in Higher Education (CNCSIS), since 1995
- Member of National Council for Titles, Diplomas and Certificates (CNATDCU), 2006–2012
- Chairman of the Engineering Sciences Panel of CNATDCU 2010-2012
- Member of the CNATDCU Computer, Information Technology and Systems Engineering Committee, 2012-2020
- Chairman of CNATDCU's Computer, Information Technology and Systems Engineering Committee, since 2020
- 24 PhD students received their PhD title under my coordination.

**Awards and Honors:**

-Correspondent member of Romanian Academy

-Correspondent member of Romanian Academy of Technical Sciences

-“Best Associate Editor Award of the IEEE Transactions on Intelligent Transportation System” in 2011 given by IEEE Intelligent Transportation Systems Society in 2012,

-”Constantin Budeanu” Romanian Academy Prize in 2009 for papers published in „Stereovision Based Sensorial Perception”,

-“Marius Hanganut” Prize of Technical University of Cluj-Napoca in 2005 for Achievements in Research Activity.

**October 2022**

**Sergiu Nedevschi**  
**Professor in Computer Science**

