Ioan URSU

1. Ph. D. Mathematics, Senior Researcher, CS I

Mailing Address

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https://bulletin.incas.ro/files/cv__i_ursu.pdf

2. SCHOOLING

High School Aurel Vlaicu, Orastie, 1964
University of Bucharest, Department of Mathematics: **B.S., Fluid Mechanics, 1969**
Polytechnic Institute of Bucharest, Department of Automatic Control: **Graduate studies, 1985-1986**
"Simion Stoilow" Institute of Mathematics of Romanian Academy: **Ph D, Mathematics, 2000**

3. EMPLOYMENT

1969-to date: INCAS - "Elie Carafoli" National Institute of Aerospace Research, Bucharest (formerly IMFDZ, formerly INCREST, formerly IMFCA, formerly ICPAS)
1969: Assistant Researcher; 1972: Scientific Researcher; 1977: Senior Researcher; 1995-2008: Head of INCAS Systems Analysis Department; 2008-2010: Head of INCAS Mechatronics Department; 2010-2014: Head of INCAS Systems Department; member of INCAS Scientific Council: 2008-to date; president of INCAS Scientific Council: 2016-2020

4. PROFESSIONAL EXPERIENCE

4.1. Specialization

(i) basic specialization
Analysis, synthesis, qualification testing and flight clearance for aircraft and helicopters hydraulic servomechanisms
From 1969, I was directly involved in all Romanian aviation projects, including IAR93 and IAR99 military jets, Puma and Alouette helicopters, and Romanian flight simulator projects. Contributions in the design and manufacturing of hydraulic servomechanisms for all these projects
(ii) research interest
Electrohydraulic and electromechanical actuators design; active and semiactive control; anti blocking systems (ABS); smart aerospace structures; structural health monitoring (SHM); stability robustness and performance robustness – analysis and synthesis; linear and nonlinear control synthesis: LQG control, backstepping control, sliding mode control, geometric control; adaptive control synthesis; intelligent control synthesis: neural control, fuzzy control

4.2. Internal Research Reports

Over 250, from 1970, until now

5. PERSONAL HONOURS AND AWARDS

♦ Chair and co-chair in several national and international conferences
♦ Co-author of "Dynamic Systems Control Methods" group of works awarded with Romanian Academy 1998 "Aurel Vlaicu" Prize
♦ Romanian Academy 2002 "Aurel Vlaicu" Prize, awarded in 2004 for the book *Active and semiactive control* (Romanian Academy Publishing House, 2002)
♦Award for Excellence: *Aircraft Engineering and Aerospace Technology*, 1998, Great Britain; Who'sWho in Science and Engineering (2006-2007 Edition)
♦Gold Medal for the patent no. RO131152B1/2017 "Procedeu complex de identificare online a defectelor mecanice în spectroscopia impedanței electromecanice, cu evitarea diagnozelor false (Complex process for on-line identification of mechanical faults in electromechanical impedance spectroscopy while preventing false diagnosis)", inventors: D. Enciu, I. Ursu, M. Tudose, awarded at the 46th Edition of the International Invention Salon held at Geneva, Switzerland, 11-15 April 2018, Gold Medal
♦Special Prize from the Turkish Patent and Trademark Office for the patent no. RO131152B1/2017 Procedeu complex de identificare online a defectelor mecanice în spectroscopia impedanței electromecanice, cu evitarea diagnozelor false (Complex process for on-line identification of mechanical faults in electromechanical impedance spectroscopy while preventing false diagnosis)", inventors: D. Enciu, I. Ursu, M. Tudose, awarded at the 46th Edition of the International Invention Salon held at Geneva, Switzerland, 11-15 April 2018

6. PROFESSIONAL AND SCIENTIFIC SERVICE AND EXPERTISE

6.1. Professional Societies Memberships: Member GAMM (Gesellschaft für Angewandte Mathematik und Mechanik), Germany; Member ROMAI (Romanian Society of Applied and Industrial Mathematics); Member Literati Club-MCB University Press (Bradford, Great Britain)
6.2. Reviewer to National and International Journals: INCAS Bulletin, Romania; Journal of The Franklin Institute, Elsevier, Philadelphia, USA (ISI); American Society of Mechanical Engineers (ASME) Journals, USA; Journal of Vibration and Control, SAGE, USA (ISI); International Journal of Control, Automation, and Systems, South Korea (ISI); Mechatronics (ISI); Aerospace Science and Technology (ISI); Sensors (ISI); IEEE Transactions on Automation Science and Engineering (ISI); Journal of Aerospace Engineering (ISI), Nonlinear Dynamics (ISI); Journal of Aircraft (ISI) etc.
6.2. Member of Journal Boards
INCAS Bulletin, ACTUATORS (mdpi Journal, IF 2.523)

6.3. Scientific Expertise

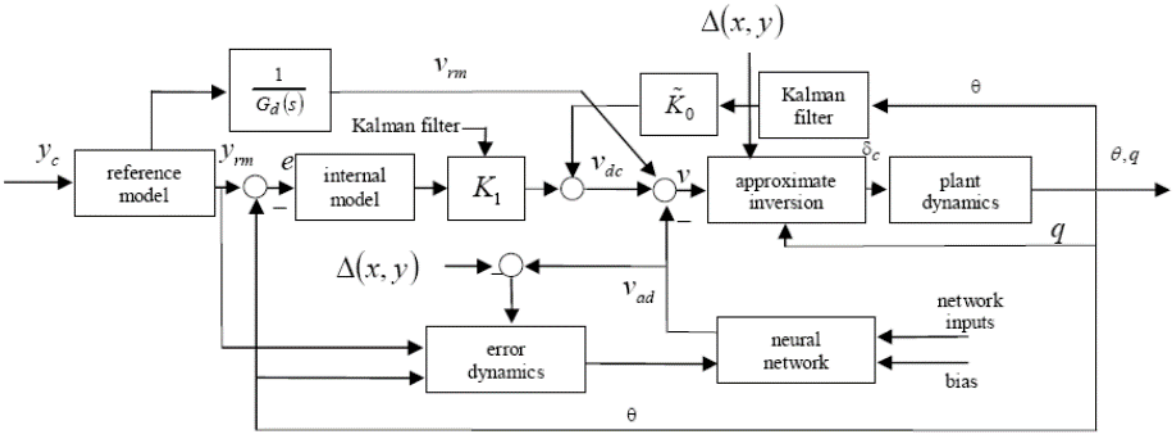
– a short listing of the main research contributions –

♦ *"Active and semiactive control"* (2002), in Romanian, authors I. Ursu, F. Ursu (2002), **Romanian Academy Publishing House**, 356 pages, a book awarded with **Aurel Vlaicu Prize by the Romanian Academy** in 2004, an overview of the

subject status around 2000. The text is thought as self-contained. The main perspective concerns problems such as: active and semiactive control of suspension systems, active and pseudoactive aeroservoelastic control, antisaturating and antichattering control, classical and artificial intelligence-based robust control synthesis. The book also shows the experience gained in the conception and realization of servomechanisms in the former aviation institute INCREST, the current INCAS.

- Two criteria of design the servo actuating flight controls are proposed in the paper *"About aeroservoelasticity criteria for electrohydraulic servomechanisms synthesis",* authors I. Ursu, M. Vladimirescu, F. Ursu, **Proceedings of 20th Congress of the International Council of the Aeronautical Sciences, ICAS 96**, vol. **2**, pp. 2335-2344: a criterion based on the servoactuator impedance function and a criterion determined by the active control of the flexible body modes of the aircraft.
- A method of designing the controller to solve the Robust Servomechanism Problem is proposed in the paper "*From robust control to antiwindup compensation of electrohydraulic servo actuators*" (1998), authors I. Ursu, F. Ursu, M. Vladimirescu, T. Sireteanu, **Aircraft Engineering and Aerospace Technology**, vol. 70, 4, 259-264 **Award for Excellence**, Great Britain. The method is based on the well-known paradigm consisting of two separate devices: a servocompensator, in fact an internal model of the exogenous dynamics, and a stabilizing compensator. The proof is made involving the servocompensator structure which is close to the one designed for step signals. The stabilizing compensator is assured by the way of a linear quadratic optimal procedure. An antiwindup compensation is added to deal with the adverse effects caused by actuator saturation.
- The absolute stability theory is used to derive sufficient absolute stability conditions for the equilibrium point of an inertial loaded electrohydraulic servo; see the paper "*About absolute stable synthesis of electrohydraulic servo*" (1999), authors I. Ursu, F. Ursu, T. Sireteanu (1999), **Technical Papers of AIAA (AIAA-99-4090)**, Guidance, Navigation and Control Conference, Portland, Oregon, USA, August 9-11, vol. **2**, pp. 848-858. The first condition represents a simplified approach, starting from the Lefschetz's inequality. The second condition represents an exactly approach, involving a stochastic framework. An extended criterion Popov-Morozan is obtained.
- Two pointing algorithms for the position control in the NOTTE experiment are presented in the paper "*Positioning Algorithms in the NOTTE Experiment*" (1999) authors I. Ursu, A. Plaian, F. Ursu, **Proceedings of ICALEPCS 99, International Conference on Accelerator and Large Experimental Physics Control Systems,** Trieste, Italy, October 4-8, CD published. One of them exploits the abilities of a predictor type Kalman estimator in a discrete time LQG synthesis, given the physical constraint of delayed incomplete state information.
- In a seminal paper "*Stability of equilibria in a four-dimensional nonlinear model of a hydraulic servomechanism*" (2004), authors A. Halanay, C. A. Safta, I. Ursu, F. Ursu, **Journal of Engineering Mathematics**, vol. 49 , 4, August, 391-405, a critical case of equilibria stability for a realistic, four dimensional, model of a mechanohydraulic servomechanism is revealed and then treated using Lyapunov-Malkin mathematical apparatus. Given the two features of electrohydraulic servomechanism − likely switching mathematical model disadvantaged once again by a critical stability − to whom is to be added the defect of relative degree, in a series subsequent papers the way of control synthesis will combine the geometric theory of nonlinear feedback and the classical Lyapunov-Malkin approach in a new configuration, that of the switched systems.
- A fuzzy logic controller for an airplane antilock-braking system (ABS) is presented in the paper "*Airplane ABS control synthesis using fuzzy logic*" (2005), authors I. **Ursu,** F. Ursu, **Journal of Intelligent & Fuzzy Systems** (USA), 16, 1, 23-32. The validated algorithm ensures the avoiding of wheel's blockage, even in the worst road conditions.
- A switching type neuro-fuzzy control synthesis for an electrohydraulic servo is proposed in the work "Neuro-fuzzy synthesis of flight controls electrohydraulic servo" (2001), authors **I. Ursu, F.** Ursu, F. and L. Iorga, **Aircraft Engineering and Aerospace Technology,** vol. 73, pp. 465-471. An experimental validation is recently reported: "*Neuro-fuzzy control synthesis for hydrostatic type servoactuators. Experimental results*" (2009), authors I. Ursu, G. Tecuceanu, A. Toader, C. Calinoiu, F. Ursu, V. Berar, **INCAS Bulletin**, vol. 1, 2, 136-150.
- In the paper "*Backstepping design for controlling electrohydraulic servos*" (2006), authors I. Ursu, F. Ursu, F. Popescu, **Journal of The Franklin Institute,** USA, vol. 343, January, 94-110, it is clarified how the standard theory of backstepping can produce a controller for a complex plant such as an electrohydraulic servo.
- The paper "H_∞ *control with* μ *-analysis of a piezoelectric actuated plate*" (2009), authors Iorga, L., H. Baruh, I. Ursu, **Journal of Vibration and Control,** vol. 15, 8, August, 1143-1171**,** develops a multimodal active H_∞ controller for piezoelectric actuated plates. The closed-loop control scheme is subject to both uncertainties due to control and observation spillover in the unmodeled residual modes and to parametric errors in the structural model. The closed-loop stability and performance robustness is analyzed using μ -analysis.
- The work "*A unitary approach on adaptive control synthesis*", (2010), authors I. Ursu, A. Toader, **Mathematics and Computers in Science and Engineering, A Series of Reference Books and Textbooks,** Edts. A. Khallel *et al.*, A. Hassairi, proposes a unitary approach of adaptive output feedback control for non-affine uncertain systems, about which

the only knowledge refers to the relative degree *r*.



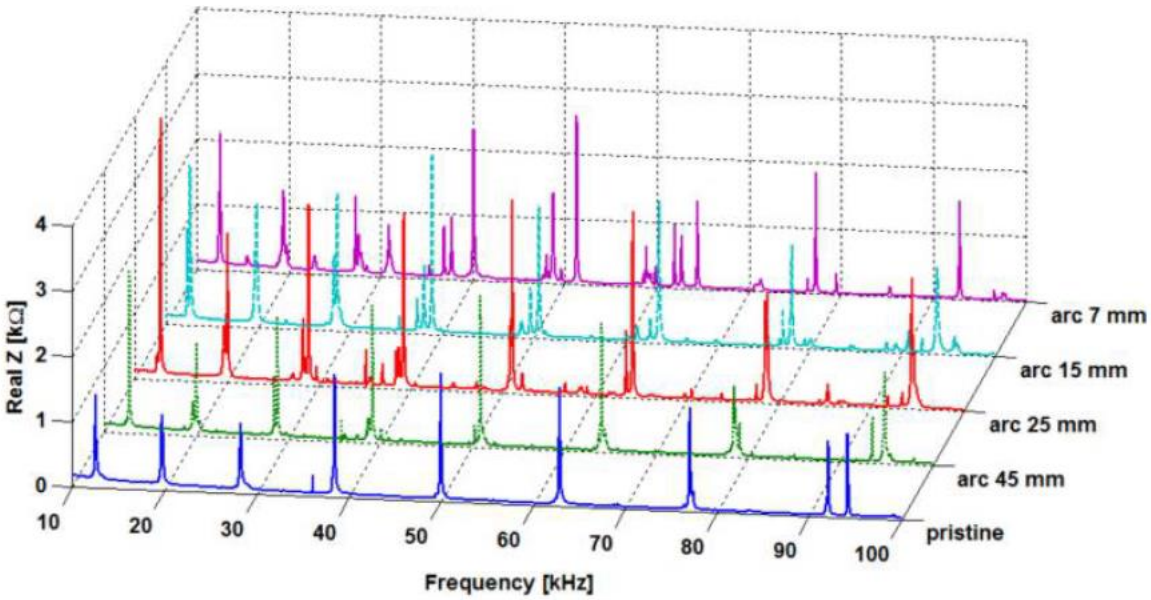
Implementation block diagram of neural network based adaptive control

- The paper "Pilot modeling based on time delay synthesis", authors A. Toader, I. Ursu, **Proceedings of the Institution of Mechanical Engineers - Part G: Journal of Aerospace Engineering**, **227**, 4, 2013, defines the pilot model synthesis in the framework of rigorous time-delay synthesis (see the next Figure). The problem is then solved by making reference to the control separation and duality principles. A closed-form expression of the solution is thereby obtained. The proposed model was then compared by numerical simulations with Kleinman and Hess consecrated models. The analysis of the results shows that this new pilot model is described by a simplified representation, instead denoting similar performance versus previous optimal models – which contains complicated insertions, as Kleinman–Baron predictor or Padé approximation, respectively. Finally, joint evaluation of the proposed model and Kleinman and Hess models with respect to the well-known Neal–Smith criterion confirms the consistency and viability of the employed strategy as a possible tool for pilot-induced oscillations phenomenon investigation.
- The article "*New stabilization and tracking control laws for electrohydraulic servomechanisms* ", authors I. Ursu, A. Toader, S. Balea, A. Halanay, appeared in the latest issue of the prestigious European Journal of Control, **19**, 1, 2013, © Elsevier. The same number present *Discussions* on the article, plus replica of the first author, Ioan Ursu. **We present quotes from the comments of some the reputable specialists.**
  - **Tingwen Huang (Texas A & M University at Qatar)**: "A novel way is provided to deal with the problem of the stabilization and tracking control for EHSs. Overall, paper provides a creative way to design the control laws for issues of the EHSs stabilization and tracking control, this study also opens several new gates for the further investigation of electrohydraulic servomechanisms (EHSs) to improve the performance of the closed-loop EHSs."
  - **MingQing Xiao (Southern Illinois University):** "It is interesting to note that after a feedback control is proposed by geometric approach, numerical simulations offered by the authors show the effectiveness for some tracking cases by using a feedback control similar to the stabilization one…In the main part, the authors present a solution of the tracking problem via backstepping approach for two types of typical tracking signals. The approach is directly based on the original system, and thus the obtained result has a better convergent performance than those by making use of geometric method, as expected. For other types of tracking signals, the proposed approach seems remain valid under some suitable assumptions. While it would appear that electrohydraulic servocontrols have reached a point where a major structural change seems unlikely, this article leads to some interesting points for a further consideration in terms of controls of EHSs."

- The article "New Results Concerning SHM Technology Qualification for Transfer on Space Vehicles", authors Enciu Daniela, I. Ursu, A. Toader, **Structural Control and Health Monitoring**, 2017, vol. 24, nr 10, https://doi.org/10.1002/stc.1992, e1992 reports some results of recent complex tests on the survival of Structural Health Monitoring (SHM) technology based on Piezo Wafer Active Sensors (PWAS) and Electromechanical Impedance Spectroscopy (EMIS) method. Successive and then concomitant action of harsh conditions of outer space, extreme temperatures and radiations, were simulated in laboratory. The tests were conducted separately on PWAS and aluminum discs as structural specimens, with PWAS bonded on them. The substantiating of the mentioned method consists in the fact that the real part of the bonded PWAS impedance spectrum, the so called EMIS structure signature, follows with fidelity the resonance behaviour of the structure vibrating under the PWAS excitation and, consequently, the onset and progress of structural damages. The conclusion of the tests is that the cumulative impact of severe conditions of temperature and radiation did not

generate the decommissioning of sensors or adhesive, which would have meant the methodology compromising. This conclusion occurs as a result of applying two new analysis methods to EMIS signatures. A first method, based on systematic observation of EMIS signatures during tests, makes it possible to distinguish the real damages, of mechanical origin, by the false ones, defined by changes caused by harsh environmental factors on the same signature. A second method, based on the concept of entropy, shows how it is possible to identify mechanical damages at a certain distance by active piezo sensor and, moreover, proved by calculation that the investigated structural specimens passed the test of SHM technology survivability.

♦ In the article Towards structural health monitoring of space vehicles, Ursu, I., Daniela Enciu, A. Toader (2016), Aircraft Engineering and Aerospace Technology, vol. 89, nr. 6, 920-927, 2017 https://doi.org/10.1108/AEAT-07-IF 0.519, The question of transfer of PWAS-EMIS-based SHM technology to space vehicles and applications received, as a novelty, a first and encouraging response.



Notes: Comparative view of pristine specimen versus four damaged specimens

6.4. Funded Research Projects

Experience (including managerial experience) in other national/international programmes/ projects:

Programme/Project	Position	Period	Budget
– "Variational processes in optimal control with free final time", Contract 6107, code CNCSIS 252	Director of Grant	2000-2002	20 000 000 lei
"Periodical solutions for nonlinear differential systems and equations with small parameters"Contract 33 457/2002, code CNCSIS 251	Director of Grant	2001-2003	70 000 000 lei
"Antiwindup control synthesis methodologies for aerospatial systems"PNCDI 1 AEROSPATIAL, Contract 54/2002, code ASR 54	Director of Project	2003-2004	681 500 000 lei
"Electrohydraulic system for movement control" PNCDI 1 AEROSPATIAL, Contract 85/2003, code ASR 31 015	Director of Project	2003-2004	3 678 258 000 lei
"Adaptive synthesis of aerospace systems based on artificial intelligence technics"PNCDI 1 AEROSPATIAL, Contract 146/2004, code ASR 41 091	Director of Project	2004-2006	140 000 RON
Analysis and conversion modules for logical and hybrid control schemas with applicability to CANDU type nuclear power plants", PNCDI 1 MENER, SubContract RAAN-SITON 168/21 09 04	Responsible of Project	2004-2006	180 000 RON

"Designing of a hydrostatic servoactuator for aicrafts", PNCDI2 of Project 81 036 SAHA	Director of Project	2007-2010	1 163 305 RON
"Development of complex active and semiactive control systems" PNCDI2 Project 71 028 DESCAS	Director of Project	2007-2010	1 047 352 RON
"Intelligent system for simultaneous control and monitoring of structures", PNCDI2 Project 81 031 SIMOCA	Director of Project	2007-2010	1 660 000 RON
"Researches concerning robust and antisaturating control using fuzzy logic and neural networks, with applocations", Project PN-II UEFISCSU ID 1391/2008	Director of Project	2008-2011	900 000 RON
Advanced strategies for high performance indoor Environmental QUAliTy in Operating Rooms, PN-II-PT-PCCA-2011-3.2-1212 EQUATOR	Responsible of Project	2012-2015	570 000 RON
Structural health monitoring in spacecraft structures using piezoelectric wafer active sensors, STAR ID 188	Responsible of Project	2012-2015	1 000 000 RON
Innovative strategies of HVAC systems for high indoor environmental quality in vehicles, PN –II t 264/2014 INSIDE	Responsible of Project	2012-2016	175 000 RON
Antiflutter demonstrator with piezoelectric actuation Contract 289/2014 for the project PN-II-PT-PCCA-2013 AFDPA	Director of Project	2014-2016	1 250 000 RON
PN-III-P1-1.2-PCCDI-2017-086, Emerging technologies to counteract the effects induced by the turbulent flows of fluid media, 2018-2021 CONTUR	Responsible of Project	2018-2020	2 000 000 RON
PN III Ctrct. 611PED/2022 „Sistem inovator inglobat in fotoliile de la bordul aeronavelor comerciale pentru reducerea transmisiei SARS-CoV-2" – acronim SAFE (Innovative seating system to reduce SARS-CoV-2 transmission on board of commercial aircrafts) SAFE	Responsible of Project	2022-2024	108 000 RON
International Project EC FP6 CESAR Cost Effective Small Aircrft	Subtask Leader	2006-2010	1 422 750 euro, a part
Programul STAR C3 2016 ADVANCED AIR DIFFUSION SYSTEM OF THE CREW QUARTERS FOR THE ISS AND DEEP SPACE HABITATION SYSTEMS (QUEST)	Responsible of Project	2017-2019	100 000 a part
International Project Clean Sky, Cleansky SMART Fixed Wing Aircraft and Cleansky robust AFC	Subtask Leader	2008-2013	9 000 000 euro, a part

♦ Director of PNCDI2 Project 81 036 – "Designing of a hydrostatic servoactuator for aicrafts", 2007-2010, Project in the framework of PNCDI II Programme of Ministry of Education and Research

Summary. There are essentially two types of electrohydraulic servoactuators: some are controlled through electro-hydraulic servovalve, others, through pump – the so-called hydrostatic servoactuator. The first type is classical, with certain advantages, among them, a faster time constant. The shortages specific to this type – energy waste, high cost for the servovalve, the necessity for a hydraulic power highway – can be counteracted through the new system, the hydrostatic servoactuator, that constituted the object of this project. This one is based on the direct connection of the hydraulic cylinder to the pump; thus, the direction of the pump rotation determines the flow rate (a closed circuit) from the pump to the hydraulic cylinder and from the hydraulic cylinder to the pump. Adding an external position loop, a servomechanism (a tracking system) is obtained. The usual internal loop for pump angular speed was avoided by static error decreasing reasons. The external loop was initially studied and then synthesized and simulated by various control laws, classical (LQG, backstepping, geometric) or unconventional (neuro-fuzzy), having as performance criterion the dynamic transients optimization, in fact, the decreasing of time constant of the system. Finally, the studies and experimental results showed that the neuro-fuzzy control not only extends the system bandwidth, but also provides excellent control performance on contrast with various classical control strategies in hydraulic servo position systems. The most meaningful feature of the nonconventional controller, experimentally validated, is the following: because is in fact a free model strategy, this methodology ensures a reduced design complexity and provides antisaturating and antichattering properties of the controlling system, thus favourising its robustness. The experimental value of the time constant: 0.08 s, versus the theoretical one: 0.09 s.

♦Director of PNCDI2 Project 71 028 – "Development of complex active and semiactive control systems", 2007-2010, Project in the framework of PNCDI II Programme of Ministry of Education and Research

Summary. The project has had as object the development, both from theoretical and experimental viewpoint, of some complex active vibration systems. The vibrations can evolve as harmful or even catastrophic phenomenon, in various physical systems, such as aerospatial vehicles, machine-tools, buildings and bridges in the presence of seismic movements etc. In fact, in the project have been proposed efficient and robust solutions and associated algorithms for semiactive and active vibration control, and also the experimental models for testing. Semiactive control can only dissipate power by means of a controllable damper. Active control is capable of both supplying and dissipating power through an actuator. In the project have been taken into account especially robust and antisaturating control solutions. First, antisaturating and antichattering semiactive control laws were considered. Secondly, Hinfinity and neuro-fuzzy active control laws were elaborated. For validation, two representative controlled systems have been performed as experimental models: the system with finite degree of freedom (two) – active vibration isolation system, and the system with infinite degree of freedom, represented by the elementary model of a cantilevered plate. Thus, three mechatronic laboratory test systems have been realized, two active systems and a semiactive one. Finally, the studies and experimental results showed that the neuro-fuzzy control provides excellent control performance on contrast with various classical control strategies. The most meaningful feature of the nonconventional controller, experimentally validated, is the following: because is in fact a free model strategy, this methodology ensures a reduced design complexity and provides antisaturating and antichattering properties of the controlling system, thus favourising its robustness. Main applications are seen in aeronautics control field but also in other areas from civil structures to robotics.

♦ Director of PN-II-PT-PCCA-2013 AFDPA "Antiflutter demonstrator with piezoelectric actuation. *Contract 289/2014"*

Summary. This project develops an advanced system for active flutter and vibration control and gust alleviation for critical aerospace applications. The practical implementation of this active flutter and vibration control approach is done through the use of high-bandwidth piezoelectric actuation embedded into a "smart wing" design. The outcome of the proposed project is a methodology and experimental confirmation of a smart-wing solution for flutter vibration control and gust alleviation.

7. PUBLICATIONS

My scholarly statistics are: h-index=15; i10-index=28; 929 citations (10 January 2023)

(https://scholar.google.com/citations?user=jEE7cjQAAAAJ&hl=en)

43 Publications in Web of Sci

Books

[B1] Ursu, I., Felicia Ursu (2002), Active and semiactive control (in Romanian), *Publishing House of the Romanian Academy*, 356 pages.

[B2] Ioan Ursu, 30 years without Noica. Exercises of love (in Romanian, 30 de ani fara Noica. Exercitii de iubire). Editura Scrisul Romanesc, Craiova, aprilie 2017.

Book Chapters

[B3]. Halanay, A., I. Ursu (2010): *Stability analysis of equilibria in a switching nonlinear model of a hydrostatic electrohydraulic actuator.* A chapter in *Mathematical Problems in Engineering Aerospace and Science*, volume 5, S. Sivasundaram (Ed.), Cambridge Scientific Publishers, ISBN 978-1-904868-79-8.

[B4] Toader, A., I. Ursu, *Towards a PIO II criterion: Improving the pilot modeling*, in Advances in Intelligent Systems and Computing Volume 187, 2013, pp 45-57, Springer-Verlag Berlin Heidelberg 2013 ISSN: 2194-5357 (Proceedings of the 2011 International Conference on Communication, Electronics and Automation Engineering http://link.springer.com/chapter/10.1007/978-3-642-32548-9_4#page-2**)**

[B5] Ursu, I., A. Toader, V. Chiroiu, S. Radnef, E. Popa, Intelligent adaptive type control for uncertain systems a chapter book in *Inverse Problems and Computational Mechanics*, vol. 1, 369-388, Romanian Academy Publishing House, 2011, ISBN 978-973-27-2147-6

[B6] C. Rugina, I. Ursu, The electromechanical impedance spectroscopy method on thin plates, in in *Inverse Problems and Computational Mechanics*, vol. II, 295-322, Romanian Academy Publishing House, 2011, ISBN 978-973-27-2708-9

[B7] Ioan Ursu, Mihai Tudose, Daniela Enciu, *Qualification of PWAS based SHM technology for space applications*". A chapter in the book STRUCTURAL HEALTH MONITORING FROM SENSING TO PROCESSING, InTechOpen, 2018

Patents

1. Patent no. 127329/30.07.2014 granted by the State Office for Inventions and Trademarks OSIM, Holder INCAS Bucharest, title of invention: **Aviation hydrostatic servoactuator**, authors: **Ioan Ursu**, Minodor Arghir, Adrian Toader, George Tecuceanu, Constantin Calinoiu.

2. D. Enciu, **I. Ursu**, M. Tudose, **Procedeu complex de identificare online a defectelor mecanice în spectroscopia impedanței electromecanice, cu evitarea diagnozelor false** (Complex method for online identification of mechanical damages using the electromechanical impedance spectroscopy, avoiding the false diagnosis), Patent no. 131152/29.12.2017.

3. I. Ursu, G. Tecuceanu, D. Enciu, A. Toader, M. Arghir, D. D. Guta Ion, D. Pepelea, C. Stoica, A. Dragos, **Procedeu complex de control activ al vibratiilor aripii de avion in prezenta turbulentei, pe baza unei metodologii emergente de identificare a modelului matematic** (Complex procedure for active control of aircraft wing vibrations in the presence of turbulence, based on an emerging methodology for identifying the mathematical model), A 2021 00378/30.06.2021

Extract List - Journal Articles in WoS Archival Journals

[33] A. Toader, I. Ursu, D. Enciu, G. Tecuceanu, Towards nonconservative conditions for equilibrium stability. Applications to switching systems with control delay, Communications in Nonlinear Science and Numerical Simulation 121 (2023) 107188, **IF 4.186**].

[32] D. Enciu, A. Halanay, A. Toader, **I. Ursu** (**2022**) Lyapunov-Malkin type approach of equilibrium stability in a critical case applied to a switched model of a servomechanism with state delay, International Journal of Control, https://doi.org/10.1080/00207179.2022.2156929, **IF 2.102**

[31] D. D. Ion-Guță, **I. Ursu**, A. Toader, D. Enciu, P. A. Dancă, I. Năstase, C. V. Croitoru, F. I. Bode, M. Sandu (**2022**) Advanced thermal manikin for thermal comfort assessment in vehicles and buildings, Applied Sciences, vol. 12, issue 4, pp. 1826; https://doi.org/10.3390/app12041826, **IF 2.838**

[30] I. Ursu, D. Enciu, G. Tecuceanu (**2019**), Equilibrium stability of a nonlinear structural switching system with actuator delay, Journal of the Franklin Institute, vol 357, no. 6, pp. 3680-3701, 2020-3 DOI: 10.1016/j.jfranklin.2020.02.035, **IF 4.504**

[29] D. Enciu, A. Halanay, **I. Ursu** (**2018**) Delay differential equation models for mechano and electrohydraulic servomechanisms used in airplane flight control, *UPB Scientific Bulletin*, Series A, vol. 80, Issue 3, **IF 0.279**

[28] D. Enciu, **I. Ursu**, A. Toader (**2017**), New Results Concerning SHM Technology Qualification for Transfer on Space Vehicles, *Structural Control and Health Monitoring*, vol. 24, issue 10, e1992, https://doi.org/10.1002/stc.1992, **IF 3.622**

[27] Ursu, I., Daniela Enciu, A. Toader (**2017**), Towards structural health monitoring of space vehicles, *Aircraft Engineering and Aerospace Technology*, vol. 89, nr. 6, 920-927, 2017 https://doi.org/10.1108/AEAT-07-**IF 0.519**

[26] C. Rugina, A. Toader, V. Giurgiutiu, **I. Ursu** (**2014**), The electromechanical impedance method for structural health monitoring of thin circular plates, *Proceedings of the Romanian Academy, Series A, Mathematics, Physics, Technical Sciences, Information Sciences*, **15**, 3, pp. 272–282, 2014. **IF. 1.658**

[25] Toader, A., **I. Ursu** (**2014**), Pilot modeling based on time delay synthesis*, Proceedings of the Institution of Mechanical Engineers - Part G: Journal of Aerospace Engineering (Proc IME G J Aero Eng)*, **228**, 5, pp. 740-754.

[24] Ursu, I., A. Toader, S. Balea and A. Halanay (**2013**), New stabilization and tracking control laws for electrohydraulic servomechanisms, *European Journal of Control ,* **19**, 1, pp. 65-80.

[23] Ursu, I., V. Chiroiu, L. Munteanu **(2012)**, Hysteresis modeling and feedforward control of a five-story system, *Proc. of the Romanian Academy, Series A: Mathematics, Physics, Technical Sciences, Information Science*, **13**, 1, 55-61, 2012.

[22] Ursu, I., G. Tecuceanu, A. Toader, C. Calinoiu **(2011)**, Switching neuro-fuzzy control with antisaturating logic. Experimental results for hydrostatic servoactuators*, Proceedings of the Romanian Academy, Series A, Mathematics, Physics, Technical Sciences, Information Science*, **12**, 3, 231-238.

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16 05 2023

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